# From Design-Time to Runtime and Back Again with Liquid Models



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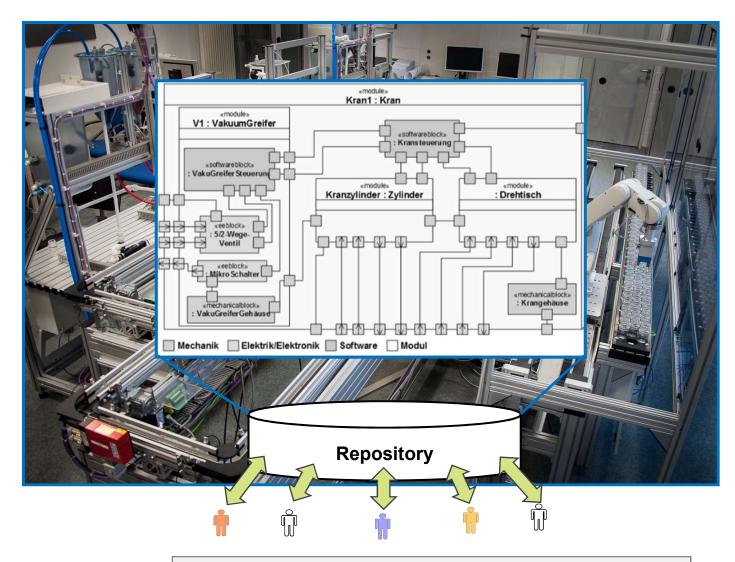




## Why Design-Time AND RUNTIME?

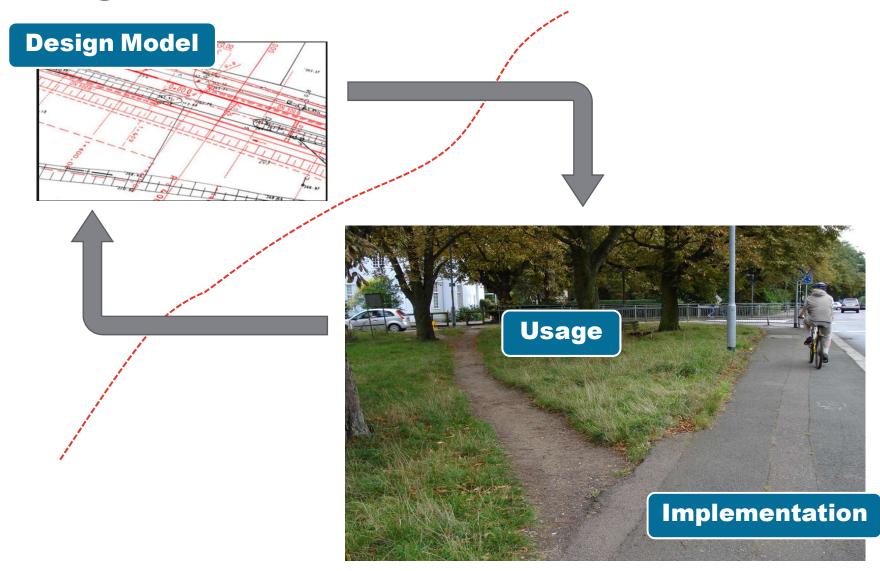


## **Software & Systems Engineering**



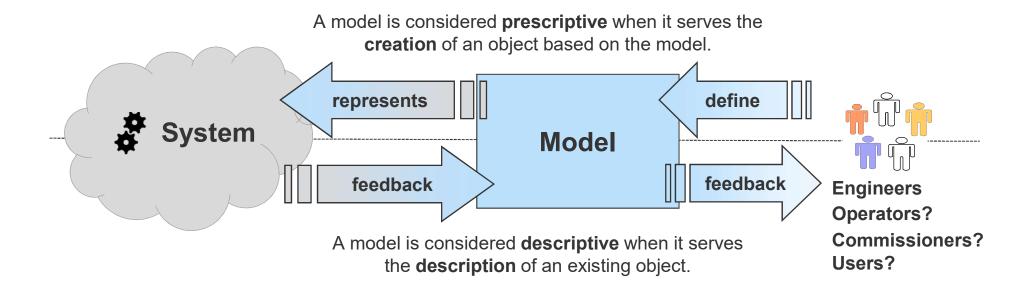


## **Design-Time versus Runtime**



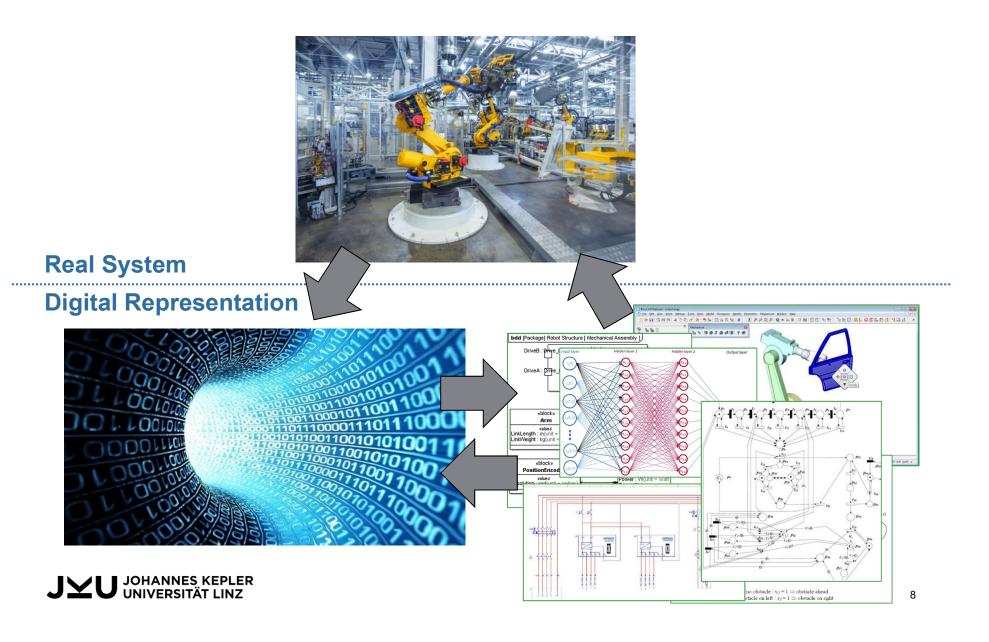


## **Revisiting Model-Driven Engineering**

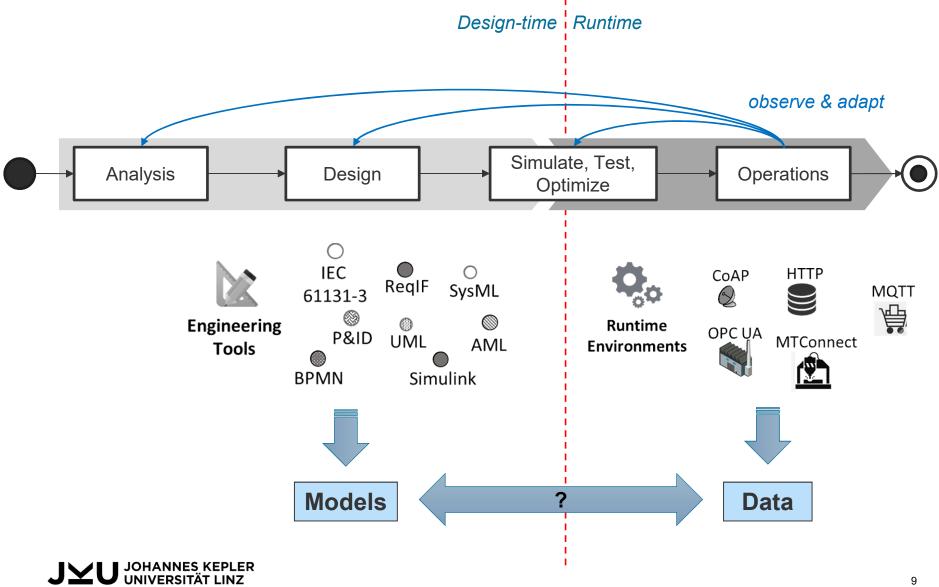




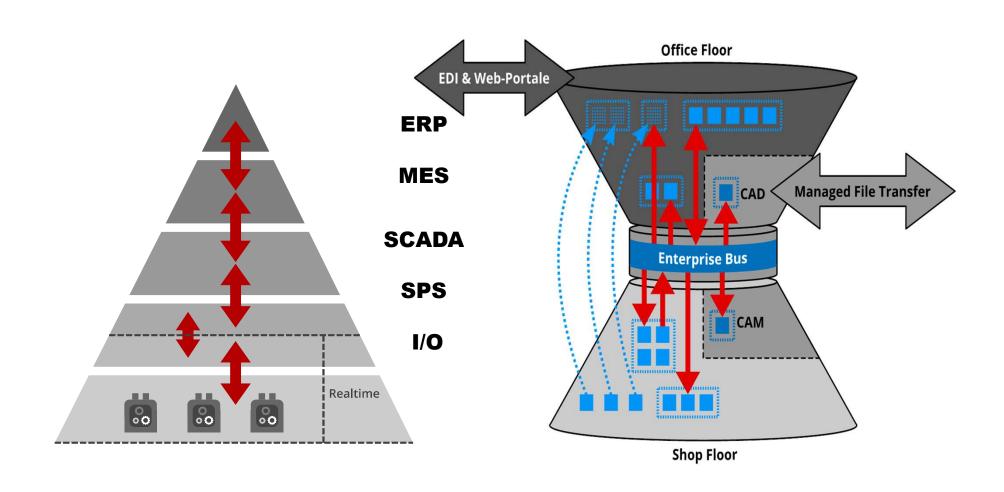
### **Example: Cyber-Physical Systems**



## **Engineering Viewpoint**



## **Operational Viewpoint**





## **Liquid Models**



#### **Towards a Platform for Liquid Models**

Model-Integrated
Smart Production
(CDL-MINT)

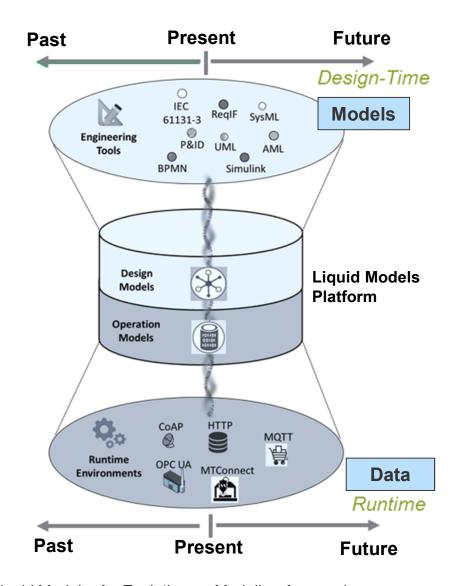
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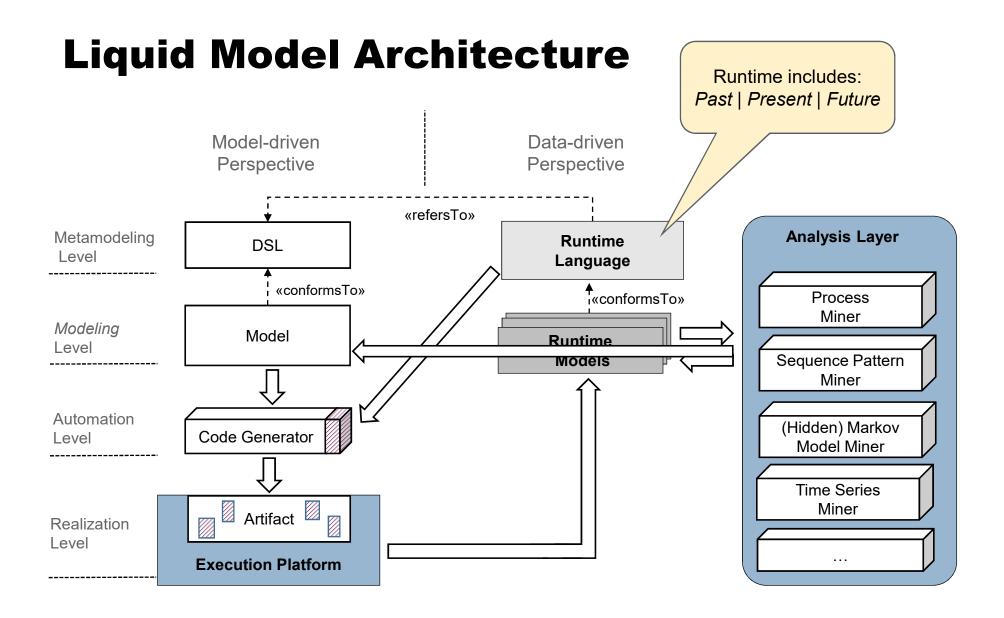








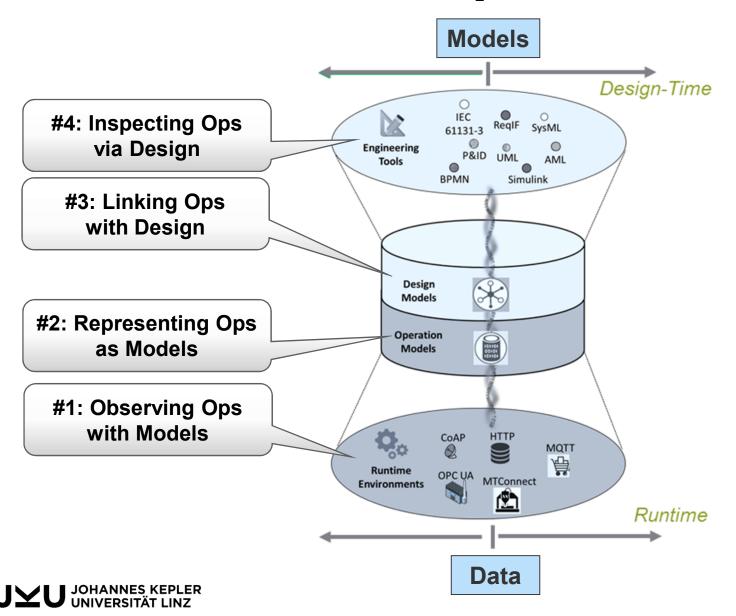




## A Tour on Selected Research Topics



### **Selected Research Topics**



## **#1: Observing Ops**with Models

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**#2: Representing Ops as Models** 



## Problem Statement, Challenge, and Contribution

Problem: Discrete design vs. continuous operation

- Systems do not switch in a time discrete manner between states
- Variables are continuously evolving to intended values of next states

Challenge: State identification

- Transform specific value configurations to states
- Precision of system realization
- Measurement uncertainty

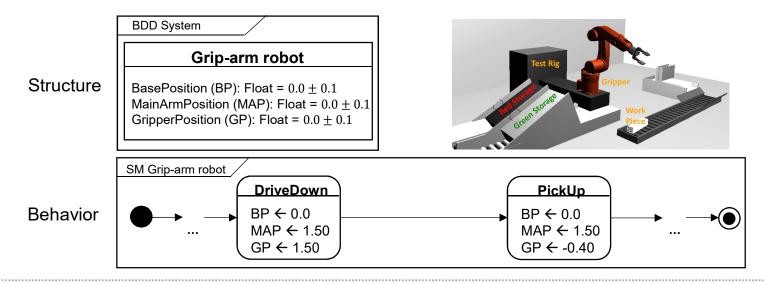
**Contribution:** Model-Driven Runtlme State identification (MD-RISE)

- Transforms values streams into event streams
- Allows to explore a system by hypothesis testing



## **Example System**

#### **Design Model**

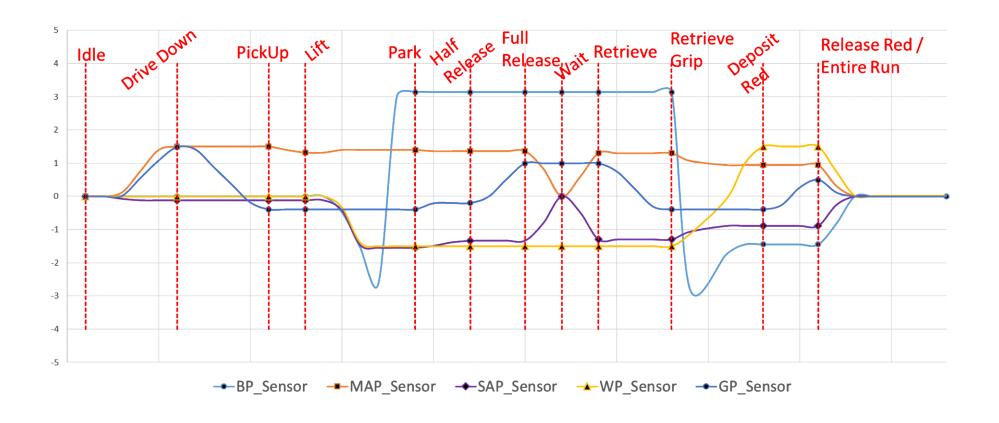


#### **Runtime Data**



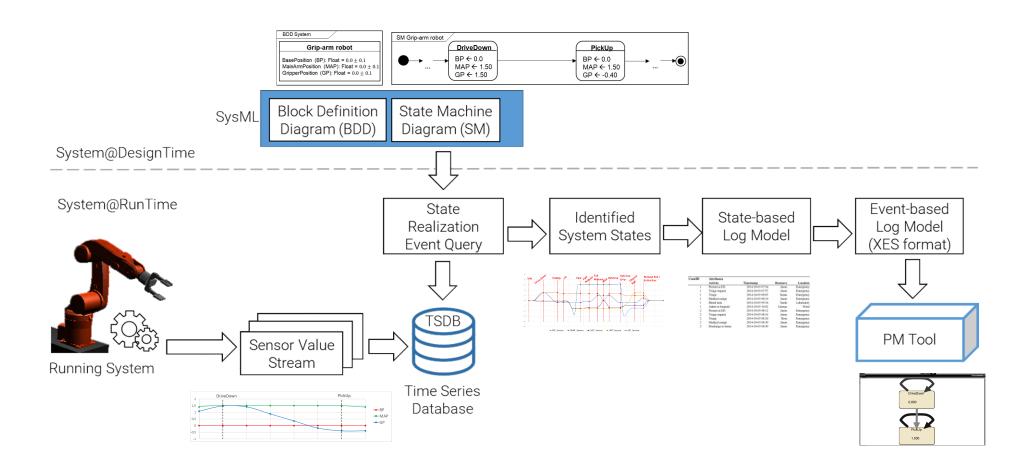


#### **State Identification: IR Problem?**





#### **MD-RISE Architecture**





#### **Evaluation Results**

#### RQ1 – Precision

- Correct recognition of states depends on
  - Tolerance range
  - Distinctness of states
  - Number of sensor

#### RQ2 - Recall

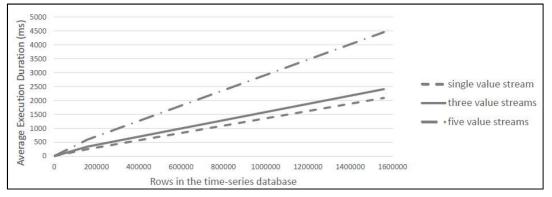
- Completeness of the states identification depends on
  - Tolerance range

#### RQ3 - Performance

- Influenced by
  - Number of data records
  - Number of sensors

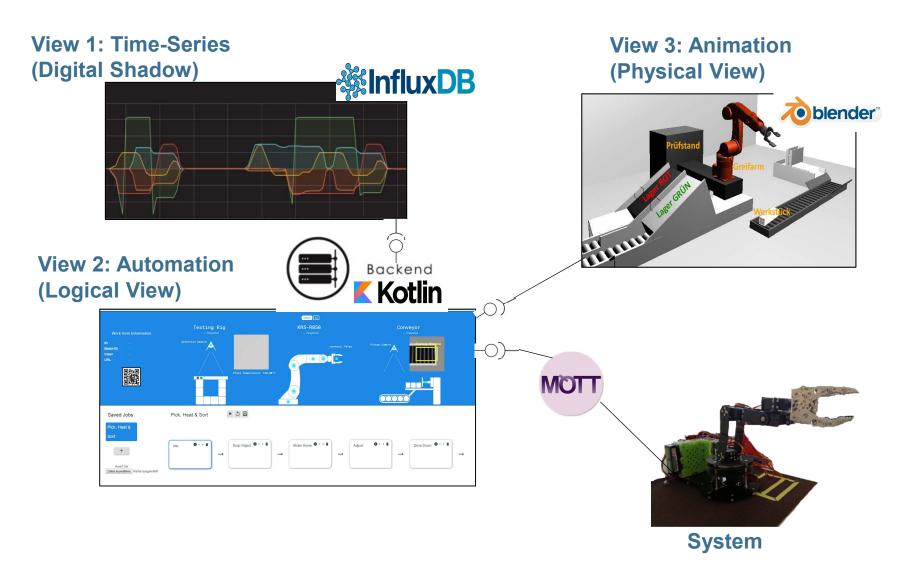
tolerance range	DriveDown			PickUp		
	precision	recall	f-measure	precision	recall	f-measure
0	NaN	0	NaN	NaN	0	NaN
0.01	NaN	0	NaN	0.08	1	0.14
0.02	1	1	1	0.08	1	0.14
0.03-0.05	1	1	1	0.07	1	0.14
0.06-0.08	1	1	1	0.07	1	0.13
0.09-0.11	0.75	1	0.86	0.07	1	0.13
0.12-0.19	0.75	1	0.86	0.07	1	0.12
0.20-0.30	0.6	1	0.75	0.05	1	0.10
0.31-0.37	0.5	1	0.67	0.05	1	0.10
0.38-0.39	0.5	1	0.67	0.05	1	0.09

tolerance range	DriveDown			PickUp		
	precision	recall	f-measure	precision	recall	f-measure
0	NaN	0	NaN	NaN	0	NaN
0.01	NaN	0	NaN	1	0.33	0.5
0.02-0.08	1	1	1	1	1	1
0.09-0.10	0.75	1	0.86	1	1	1
0.11-0.12	0.75	1	0.86	0.6	1	0.75
0.13-0.16	0.75	1	0.86	0.5	1	0.67
0.17-0.18	0.75	1	0.86	0.43	1	0.6
0.19	0.75	1	0.86	0.25	1	0.4
0.20-0.21	0.6	1	0.75	0.25	1	0.4
0.22-0.3	0.6	1	0.75	0.23	1	0.375
0.31-0.39	0.5	1	0.67	0.23	1	0.375





#### **Multi-View Digital Shadow Platform**



## #3: Linking Ops with Design

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#4: Inspecting Ops via Design



## Problem Statement, Challenge, and Contribution

**Problem:** Text-based traces for collecting logging messages

- Long, difficult, often unstructured
- Reasoning and analyzing on isolated text files is limited

Challenge: Provide semantically enhanced logs

- Align runtime data to design models
- Define analysis through design models

#### Contribution: Temporal models

- Introduce runtime history viewpoints in modeling languages
- Define runtime analysis on model level as queries or derived properties

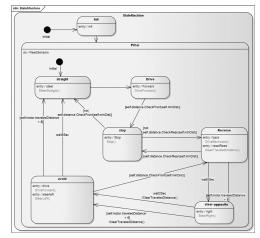


#### **Example Systems**

## System 1: PiCar



#### Design Model



#### **Runtime Data**

caseID;timestamp;Sender;Receiver;Message;ParameterValue;kind 1;2017-02-27 17:38:13.914;Car;Car;InitAll;none;REQ 1;2017-02-27 17:38:13.917;Car;DistanceSensors;InitSensors;none;REQ 1;2017-02-27 17:38:13.928;DistanceSensors;Car;InitReader;none;RES 1;2017-02-27 17:38:13.934;Car;MotorControl;InitializeMotor;none;REQ 1;2017-02-27 17:38:13.950;MotorControl;Car;InitializeMotor;none;RES 1;2017-02-27 17:38:13.954;Car;ServoControl;InitializeServo;none;REQ 1;2017-02-27 17:38:13.964;ServoControl;Car;InitializeServo;none;RES 1;2017-02-27 17:38:13.991;Car;Car;SteerStraight;none;REQ 1;2017-02-27 17:38:13.992;Car;ServoControl;SteerTo;direction=7;REQ 1;2017-02-27 17:38:15.145;ServoControl;Car;SteerTo;direction=7;RES 1;2017-02-27 17:38:15.147;Car;Car;SteerStraight;none;RES

#### JYU JOHANNES KEPLER UNIVERSITÄT LINZ

#### Design Model

InstanceOfUR10

RR RoleRequirements: ArticulatedRobot

RR RoleRequirements: IODevice

RRI RoleRequirements: EthernetPhysicalDevice

(A) IE EthernetCommunicationModule

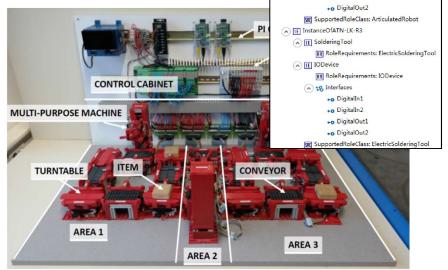
→o DigitalIn2

DigitalOut1

▲ S Interfaces

DigitalIn1

## System 2: IAF Plant

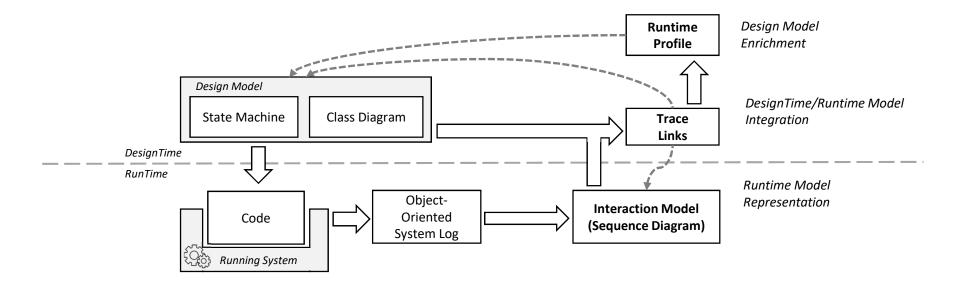


#### **Runtime Data**

 $\label{eq:Fields:component} \ \ \text{timestamp, item} \\ \text{entered } -\text{/IAF/a2/t1,2017} - 02 - 08 - 23 - 28 - 51,923\,\text{b4ff191d5} \\ \text{entered } -\text{/IAF/a2/c1,2017} - 02 - 08 - 23 - 28 - 54,923\,\text{b4ff191d5} \\ \text{entered } -\text{/IAF/a2/t1,2017} - 02 - 08 - 23 - 28 - 57,83\,\text{e}\,\text{5f}\,\text{507}\,\text{cff2} \\ \text{entered } -\text{/IAF/a2/t2,2017} - 02 - 08 - 23 - 28 - 61,923\,\text{b4ff191d5} \\ \text{entered } -\text{/IAF/a2/c1,2017} - 02 - 08 - 23 - 28 - 63,83\,\text{e}\,\text{5f}\,\text{507}\,\text{cff2} \\ \text{entered } -\text{/IAF/a2/m1,2017} - 02 - 08 - 23 - 28 - 69,923\,\text{b4ff191d5} \\ \text{entered } -\text{/IAF/a2/t1,2017} - 02 - 08 - 23 - 28 - 74,5673647866d4} \\ \dots \\$ 



- UML/SysML already provide runtime viewpoints
  - o Object diagram, interaction diagrams, ...
- Injecting logs into UML/SysML models as linked elements
- Profiles for computing aggregated runtime information





### **EA Sequence Miner**



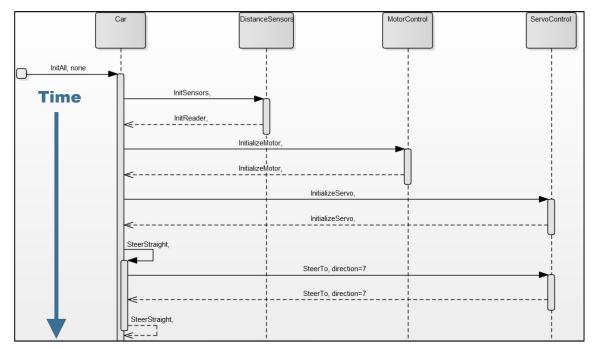
## Execution logs as UML Sequence Diagrams

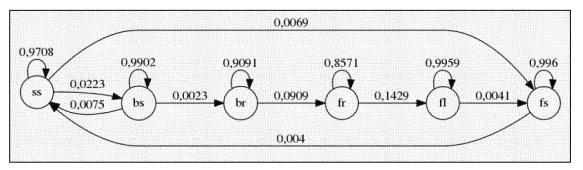
- Communication between components via messages
- Standard UML
- Play-in/play-out sequences
- Filters, queries, and transformations



#### **MotorControl** ServoControl

- drive\_forward (f)steer\_left (l)
- drive\_backward (b) steer\_straight (s)
- stop (s)
- steer\_right (r)

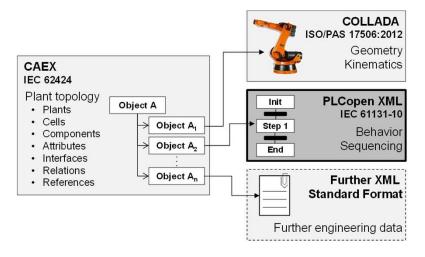


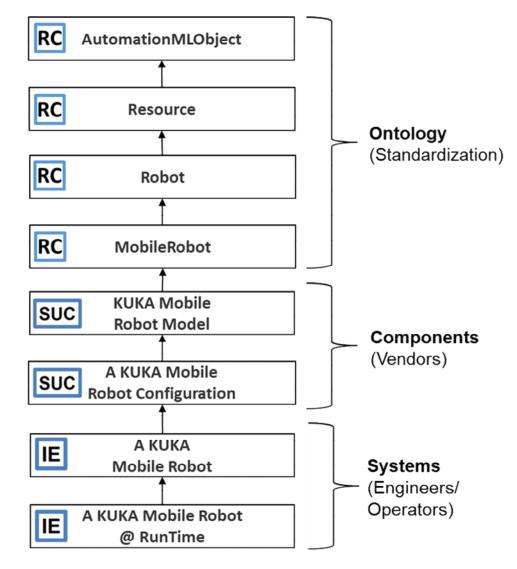




## Capturing Runtime in <AutomationML/>

- AutomationML lacks runtime viewpoints
- But allows language inherent extensions
- Maps to standardized operational frameworks



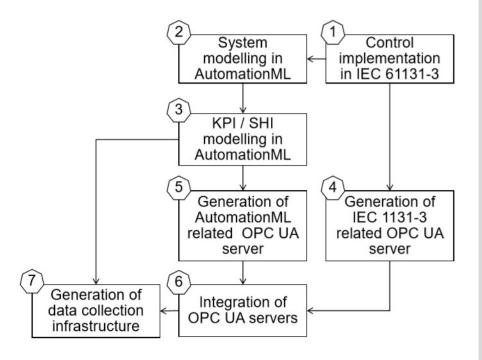




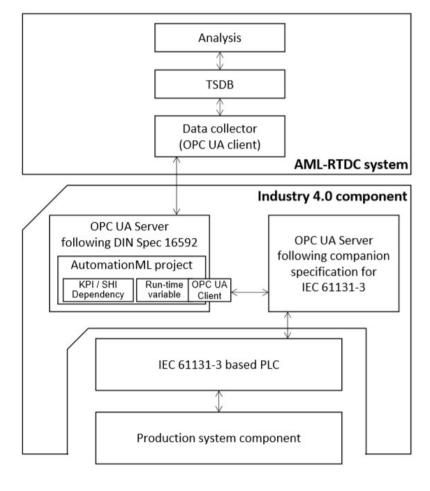
Mayerhofer, Wimmer, Berardinelli, Drath: *A Model-Driven Engineering Workbench for CAEX - Supporting Language Customization and Evolution*. IEEE Trans. Industrial Informatics 14(6): 2770-2779 (2018)

#### <a href="#">AutomationML/> Runtime Extension</a>

## Modeling & Generation Process



#### **Runtime Architecture**

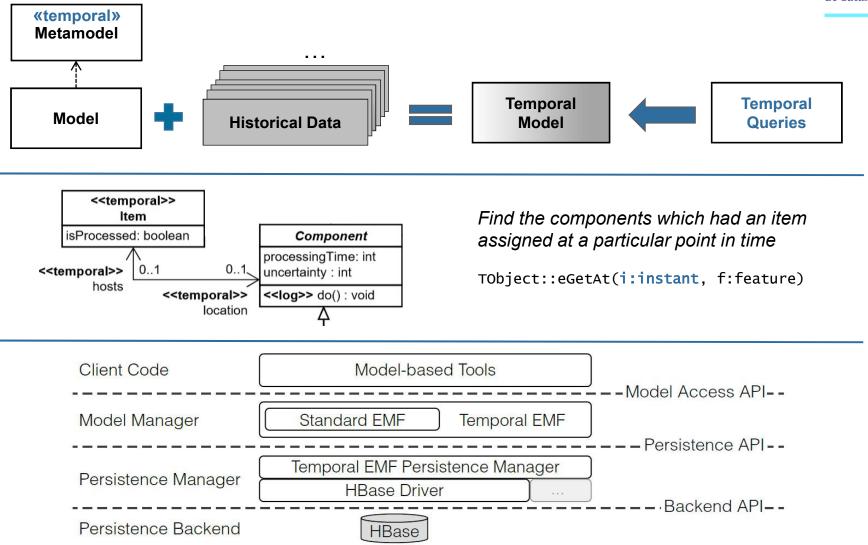




Mazak, Lüder, Wolny, Wimmer, Winkler, Kirchheim, Rosendahl, Bayanifar, Biffl: *Model-based generation of run-time data collection systems exploiting AutomationML*. Automatisierungstechnik 66(10): 819-833 (2018)



#### **Capturing Runtime in any DSL**



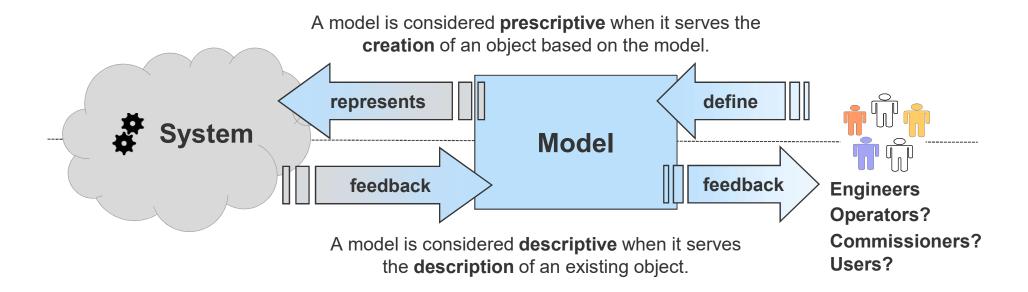


## Conclusion & Outlook



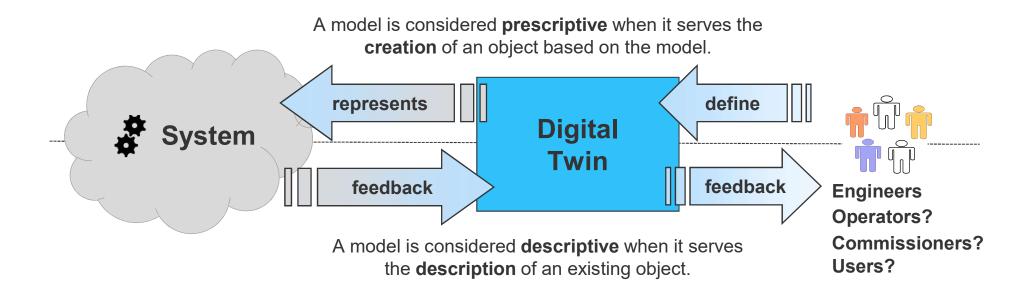


#### From MDE...





## ... to Digital Twins





## **Digital Twin Engineering**

#### Digital Model

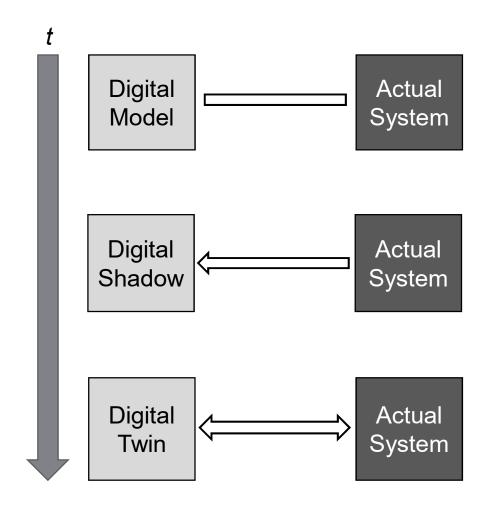
- Documentation & communication
- Simulation & code generation
- Design-space exploration
- Commissioning

#### Digital Shadow

- State inspection
- Runtime monitoring
- Predictive reasoning
- Conformance checking

#### Digital Twin

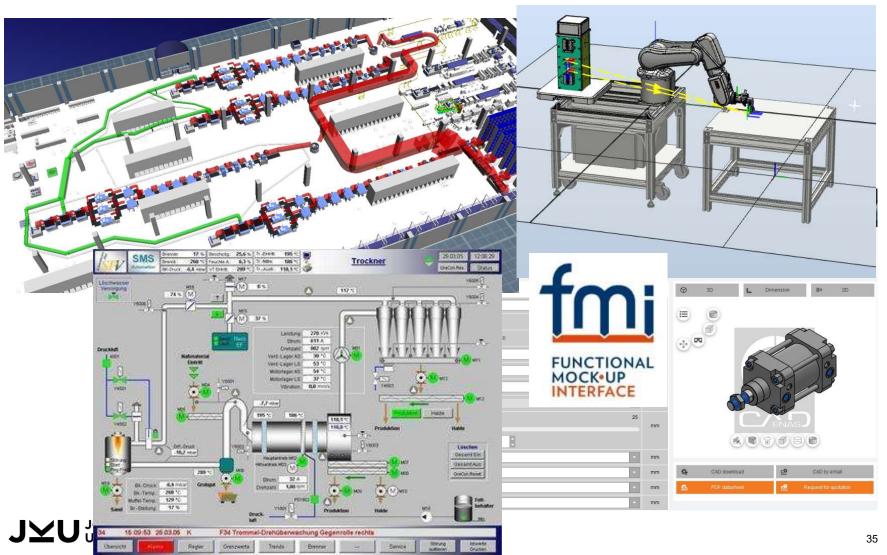
- Runtime adaptation
- Live updates & rollbacks
- Decision making
- Autonomy



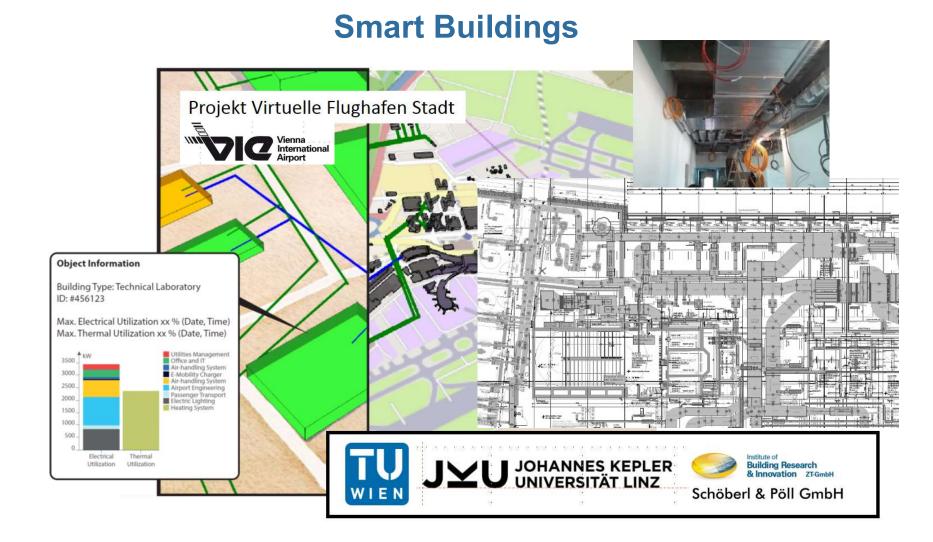


## **Emerging Digital Twin Domains (1/4)**

#### **Smart Production**



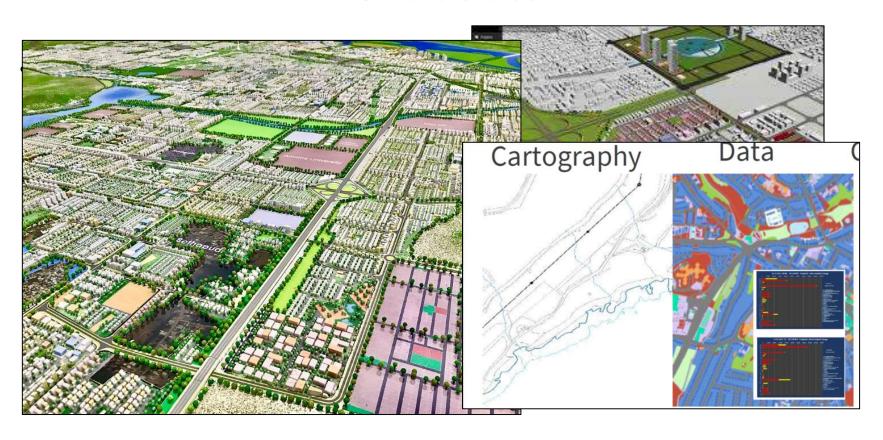
## **Emerging Digital Twin Domains (2/4)**





## **Emerging Digital Twin Domains (3/4)**

#### **Smart Cities**

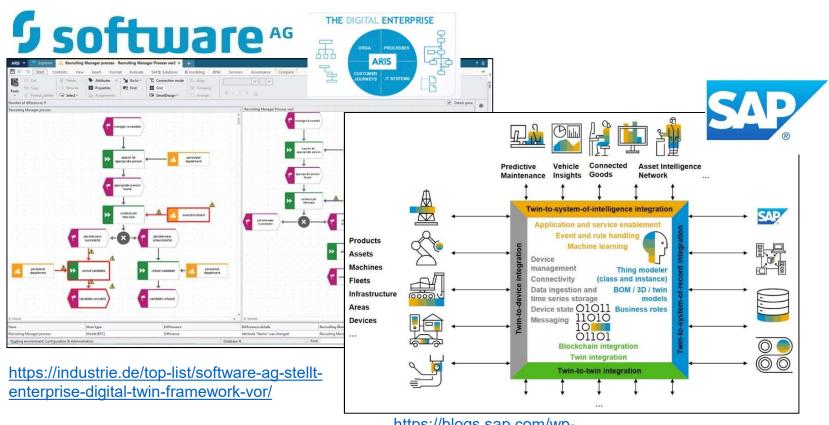


Amaravati, the new capital of the Indian state of Andhra Pradesh, is thought to be the first entire city born with a digital twin.



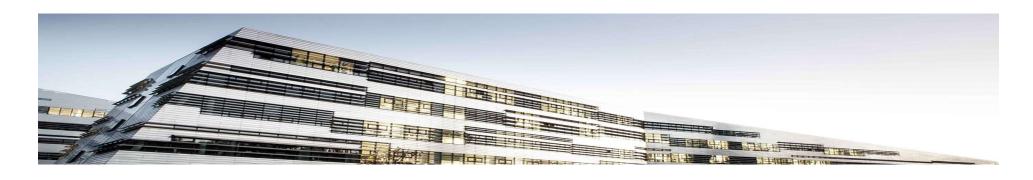
## **Emerging Digital Twin Domains (4/4)**

#### **Smart Enterprise**



https://blogs.sap.com/wp-content/uploads/2017/09/Digital Twin Implementation.jpg





## Thank you! Comments? Questions? Feedback?

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## **Publications (1/2)**

- Wolny, Mazak, Wimmer: Automatic Reverse Engineering of Interaction Models from System Logs. ETFA 2019
- Wolny, Mazak, Wimmer, Huemer: Model-driven Runtime State Identification.
   EMISA 2019
- Mazak, Lüder, Wolny, Wimmer, Winkler, Kirchheim, Rosendahl, Bayanifar, Biffl: *Model-based generation of run-time data collection systems exploiting AutomationML*. Automatisierungstechnik 66(10): 819-833 (2018)
- Wolny, Mazak, Wimmer, Konlechner, Kappel: Model-Driven Time-Series
   Analytics. Enterprise Modelling and Information Systems Architectures 13: 252-261 (2018)
- Gómez, Cabot, Wimmer: TemporalEMF: A Temporal Metamodeling Framework. ER 2018: 365-381



## Publications (2/2)

- Bill, Mazak, Wimmer, Vogel-Heuser: *On the Need for Temporal Model Repositories*. STAF Workshops 2017: 136-145
- Mazak, Wimmer, Patsuk-Boesch: Reverse engineering of production processes based on Markov chains. CASE 2017: 680-686
- Wolny, Mazak, Konlechner, Wimmer: Towards Continuous Behavior Mining.
   SIMPDA 2017: 149-150
- Mazak, Wimmer, Patsuk-Bösch: Execution-Based Model Profiling. SIMPDA 2016: 37-52
- Mazak, Wimmer: On Marrying Model-driven Engineering and Process Mining:
   A Case Study in Execution-based Model Profiling. SIMPDA 2016: 78-88
- Mazak, Wimmer: Towards Liquid Models: An Evolutionary Modeling Approach.
   CBI 2016: 104-112

